



# Uniqueness of solution of a generalized $\star$ -Sylvester equation

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Joint work with **B. Iannazzo**

# Generalized $\star$ -Sylvester equation

Given  $A, B, C, D, E \in \mathbb{C}^{n \times n}$

**Goal:** Find necessary and sufficient conditions for the equation

$$AXB + CX^{\star}D = E \quad \text{generalized } \star\text{-Sylvester equation}$$

to have a **unique solution**.

( $X \in \mathbb{C}^{n \times n}$ , unknown)

( $\star = \top$  or  $*$ )

# Motivation

- Natural extension of  $AX + X^*D = E$ .
  - Numerical methods for palindromic eigenvalue problems [Byers-Kressner'06], [Kressner-Schröder-Watkins'09], [Dmytryshyn-Kågstöm'15]
  - Congruence orbits ( $D = A, E = 0$ ) [D.-Dopico'11]

- Closely related to  $AXB + CXD = E$  [Chu'87]

- Iterative algorithms for solving  $\sum_{i=1}^r A_i X B_i + \sum_{j=1}^s C_j X^T D_j = E$

[Wang-Cheng-Wei'07], [Xie-Ding-Ding'09], [Li-Wang-Zhou-Duan'10], [Song-Chen'11], [Song-Chen-Zhao'11], [Song-Feng-Whang-Zhao'14],...

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# Which kind of characterization are we looking for?

$$\Lambda(A - \lambda B) = \text{Spectrum of } A - \lambda B$$

Theorem (Uniqueness of solution for generalized Sylvester) [Chu'87]

The equation  $AXB - CXD = E$  has a **unique solution** iff  $A - \lambda C$  and  $D - \lambda B$  are **regular** and  $\Lambda(A - \lambda C) \cap \Lambda(D - \lambda B) = \emptyset$ .

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# Which kind of characterization are we looking for? (cont.)

☞ Know conditions for  $AXB - CXD = E$  and  $AX + X^*D = E$ :  
in terms of **spectral properties** of **matrix pencils** constructed  
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# Which kind of characterization are we looking for? (cont.)

☞ Know conditions for  $AXB - CXD = E$  and  $AX + X^*D = E$ :  
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**Q: Analogous characterization** for  $AXB + CX^*D = E$  ??

# The vec approach

$\text{vec}(AXB + CX^*D) = \text{vec}(E)$  leads to

- $\boxed{\star = \top}$ :  $[B^T \otimes A + \Pi(C \otimes D^T)] \text{vec}(X) = \text{vec}(E)$
- $\boxed{\star = *}$ :  $(B^T \otimes A) \text{vec}(X) + \Pi(C \otimes D^T) \text{vec}(\bar{X}) = \text{vec}(E)$

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👉  $AXB + CX^*D = E$  can be written as a linear system  $MY = b$ :

$$Y = \begin{cases} \text{vec}(X), & \text{if } \star = \top \\ [\text{vec}(\text{Re } X); \text{vec}(\text{Im } X)], & \text{if } \star = * \end{cases}$$

## The vec approach (cont.)

$$M \in \begin{cases} \mathbb{C}^{n^2 \times n^2}, & \text{if } \star = \top, \\ \mathbb{R}^{(2n^2) \times (2n^2)}, & \text{if } \star = * \end{cases}$$

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$$\begin{array}{c} AXB + CX^*D = E \text{ has a unique solution} \\ \Updownarrow \\ AXB + CX^*D = 0 \text{ has a unique solution} \end{array}$$



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$AXB + CX^*D = E$  has a unique solution



$AXB + CX^*D = 0$  has a unique solution

👉 We only need to look at the **homogeneous** equation!

# Two basic preparatory results

## Lemma 1

If  $AXB + CX^*D = 0$  has a **unique solution**, then

- (a) At least one of  $A, C$  is **invertible**.
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**Proof.** (a) If  $A, C$  both singular, then  $Au = 0 = Cv$ , with  $u, v \neq 0 \Rightarrow X = uv^*$  is a **nonzero solution**.

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$\Rightarrow$  We will see that also one of  $A, D$ , and one of  $B, C$  must be **invertible!**



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**Proof.** ( $\Leftarrow$ ):  $AXB + X^* = 0$  ( $X \neq 0$ )  $\Rightarrow (AB^*)(X^*A^*) + AX = 0$ , so

$Y = (AX)^* \neq 0$  is solution of  $AB^*Y + Y^* = 0$ .

( $\Rightarrow$ ):  $AB^*Y + Y^* = 0$  ( $Y \neq 0$ )  $\Rightarrow X = B^*Y \neq 0$  is a solution of  $AXB + X^* = 0$ .  $\square$

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$AXB + CX^*D = 0$  has a **unique solution** if and only if

- (a)  $A$  is **invertible** and  $D^*A^{-1}CY + Y^*B = 0$  has a **unique solution**, or
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- $\star = \top$ : If  $1 \neq \lambda \in \Lambda(A - \lambda D^\top)$ , then  $(1/\lambda) \notin \Lambda(A - \lambda D^\top)$ , and  $m_1(A - \lambda D^\top) \leq 1$ .

Two different proofs:

- [BK'06] ( $\star = \top$ ): Relies on some continuity arguments of operators.  
[KSW'09] ( $\star = *$ )
- [D-Dopico-Guillery-Montealegre-Reyes'11]: Using The **Kronecker canonical form** of  $A + \lambda B^*$ .

# Characterization for $\star$ -Sylvester (again)

**Theorem** (Uniqueness of solution for  $\star$ -Sylvester) [Byers-Kressner'06, Kressner-Schröder-Watkins'09]

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$S \subseteq \mathbb{C} \cup \{\infty\}$  is

- **reciprocal free** if  $\lambda \neq \mu^{-1}$  for all  $\lambda, \mu \in S$
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# Characterization of uniqueness of solution

**Theorem** (Uniqueness for generalized  $\star$ -Sylvester)

$AXB + CX^*D = E$  has a **unique solution** if and only if the pencil

$$P(\lambda) := \begin{bmatrix} \lambda D^* & B^* \\ A & \lambda C \end{bmatrix}$$

is **regular** and:

- $\boxed{\star = *}$ :  $\Lambda(P)$  is  $\star$ -reciprocal free.
- $\boxed{\star = \top}$ :  $\Lambda(P) \setminus \{\pm 1\}$  is reciprocal free and  $m_1(P) = m_{-1}(P) \leq 1$ .

**Remark:**  $m_\lambda(P) = m_{-\lambda}(P)$

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# Proof of the main result

$AXB + CX^*D = E$  has unique sol.  $\Leftrightarrow P(\lambda) := \begin{bmatrix} \lambda D^* & B^* \\ A & \lambda C \end{bmatrix}$  regular and  $\begin{matrix} \star = * \\ \star = \top \end{matrix} \Lambda(P)$   $\star$ -rec, free  
 $\Lambda(P) \setminus \{\pm 1\}$  rec. free,  $m_{\pm 1}(P) \leq 1$

## Proof:

- $A$  invertible:  $\det P(\lambda) = \pm \det(A) \det(B^* - \lambda^2 D^* A^{-1} C)$

$$\begin{bmatrix} 0 & I \\ I & -\lambda D^* A^{-1} \end{bmatrix} \begin{bmatrix} \lambda D^* & B^* \\ A & \lambda C \end{bmatrix} = \begin{bmatrix} A & \lambda C \\ 0 & B^* - \lambda^2 D^* A^{-1} C \end{bmatrix}.$$

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$$\begin{bmatrix} \lambda I & -\lambda B^* C^{-1} \\ 0 & I \end{bmatrix} \cdot \begin{bmatrix} \lambda D^* & B^* \\ A & \lambda C \end{bmatrix} = \begin{bmatrix} \lambda^2 D^* - B^* C^{-1} A & 0 \\ A & \lambda C \end{bmatrix}.$$



# Proof of the main result

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- $C$  invertible:  $\det P(\lambda) = \pm \det(C) \det(B^* C^{-1} A - \lambda^2 D^*)$

## Recall:

$AXB + CX^*D = 0$  has a unique solution iff

- $A$  is **invertible** and  $D^* A^{-1} C Y + Y^* B = 0$  has a unique solution, or
- $C$  is **invertible** and  $B^* C^{-1} A Y + Y^* D = 0$  has a unique solution.

$AX + X^*D = E$  has unique solution iff  $A - \lambda D^*$  is **regular** and:

- $\star = *$ :  $\Lambda(A - \lambda D^*)$  is  $\star$ -reciprocal free.
- $\star = \top$ :  $\Lambda(A - \lambda D^{\top}) \setminus \{1\}$  is reciprocal free, and  $m_1(A - \lambda D^{\top}) \leq 1$ .

# The periodic Schur decomposition

## Theorem [Bojanczyk-Golub-Van Dooren'92]

There are  $U_1, U_2, V_1, V_2$  unitary such that

$$\begin{aligned} U_1 A V_1 &= T_A, & U_1 C V_2 &= T_C, \\ U_2 B^* V_1 &= T_B^*, & U_2 D^* V_2 &= T_D^*, \end{aligned}$$

with  $T_A, T_B^*, T_C, T_D^*$  **upper triangular**.

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Connection with the pencil  $P(\lambda)$ :

$$\begin{bmatrix} U_2 & \\ & U_1 \end{bmatrix} \begin{bmatrix} \lambda D^* & B^* \\ A & \lambda C \end{bmatrix} \begin{bmatrix} V_1 & \\ & V_2 \end{bmatrix} = \begin{bmatrix} \lambda T_D^* & T_B^* \\ T_A & \lambda T_C \end{bmatrix}$$

# An $O(n^3)$ algorithm

(Based on the algorithm in [D-Dopico'11] for  $AX + X^T D = E$ , outlined in [Chiang-Chu-Lin'12])

$$\begin{array}{c} \triangle \\ \text{\scriptsize } T_A \end{array} \cdot \begin{array}{|c|} \hline X \\ \hline \end{array} \cdot \begin{array}{c} \triangle \\ \text{\scriptsize } T_B \end{array} + \begin{array}{c} \triangle \\ \text{\scriptsize } T_C \end{array} \cdot \begin{array}{|c|} \hline X^T \\ \hline \end{array} \cdot \begin{array}{c} \triangle \\ \text{\scriptsize } T_D \end{array} = E$$

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$X_{11}$	...	$X_{1,k-1}$	$X_{1k}$
$\vdots$	$\ddots$	$\vdots$	$\vdots$
$X_{k-1,1}$	...	$X_{k-1,k-1}$	$X_{k-1,k}$
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 \\
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 \end{array}$$

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 \begin{array}{c} \square \\ \text{\scriptsize } T_A \\ \triangle \end{array} \cdot \begin{array}{c} \square \\ X \\ \square \end{array} \cdot \begin{array}{c} \triangle \\ \text{\scriptsize } T_B \\ \square \end{array} + \begin{array}{c} \square \\ \text{\scriptsize } T_C \\ \triangle \\ \text{\scriptsize } T_C \end{array} \cdot \begin{array}{c} \square \\ X^T \\ \square \end{array} \cdot \begin{array}{c} \triangle \\ \text{\scriptsize } T_D \\ \square \end{array} = E
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$X_{11}$	...	$X_{1,k-1}$	$X_{1k}$
$\vdots$	$\ddots$	$\vdots$	$\vdots$
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 \begin{array}{c} \triangle \\ \text{---} \\ \triangle \end{array} T_A & \cdot & \begin{array}{c} \square \\ X \\ \square \end{array} \\
 \begin{array}{c} \square \\ \text{---} \\ \square \end{array} T_A & \cdot & \begin{array}{c} \square \\ X \\ \square \end{array} \\
 \end{array} \cdot \begin{array}{c} \begin{array}{c} \square \\ \text{---} \\ \square \end{array} T_B \\
 \begin{array}{c} \square \\ \text{---} \\ \square \end{array} T_B \\
 \end{array} + \begin{array}{c} \begin{array}{c} \triangle \\ \text{---} \\ \triangle \end{array} T_C \\
 \begin{array}{c} \square \\ \text{---} \\ \square \end{array} T_C \\
 \end{array} \cdot \begin{array}{c} \square \\ X^T \\ \square \end{array} \cdot \begin{array}{c} \begin{array}{c} \square \\ \text{---} \\ \square \end{array} T_D \\
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 \end{array} = E
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$\vdots$	$\ddots$	$\vdots$	$\vdots$
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$X_{11}$	...	$X_{1,k-i}$	...	$X_{1k}$
$\vdots$	$\ddots$	$\vdots$	$\vdots$	$\vdots$
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$\vdots$	$\ddots$	$\vdots$	$\ddots$	$\vdots$
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$$\begin{array}{c}
 \begin{array}{ccc}
 \begin{array}{c} \diagdown \\ \text{---} T_A \\ \diagup \end{array} & \cdot & \begin{array}{c} \blacksquare \\ X \\ \blacksquare \end{array} & \cdot & \begin{array}{c} \begin{array}{c} \diagdown \\ \text{---} T_B \\ \diagup \end{array} \\ \begin{array}{c} \blacksquare \\ \text{---} \\ \diagup \end{array} \end{array} & + & \begin{array}{ccc}
 \begin{array}{c} \diagdown \\ \text{---} T_C \\ \diagup \end{array} & \cdot & \begin{array}{c} \blacksquare \\ X^T \\ \blacksquare \end{array} & \cdot & \begin{array}{c} \begin{array}{c} \diagdown \\ \text{---} T_D \\ \diagup \end{array} \\ \begin{array}{c} \blacksquare \\ \text{---} \\ \diagup \end{array} \end{array} & = & E \\
 \begin{array}{c} \begin{array}{c} \blacksquare \\ \text{---} \\ \diagup \end{array} \\ \begin{array}{c} \diagdown \\ \text{---} T_A \\ \diagup \end{array} \end{array} & \cdot & \begin{array}{c} \blacksquare \\ X \\ \blacksquare \end{array} & \cdot & \begin{array}{c} \begin{array}{c} \diagdown \\ \text{---} T_B \\ \diagup \end{array} \\ \begin{array}{c} \blacksquare \\ \text{---} \\ \diagup \end{array} \end{array} & + & \begin{array}{ccc}
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 \end{array}$$

$X_{11}$	$\dots$	$X_{1,k-i}$	$\dots$	$X_{1k}$
$\vdots$	$\ddots$	$\vdots$	$\vdots$	$\vdots$
$X_{k-i,1}$	$\dots$	$X_{k-i,k-i}$	$\dots$	$X_{k-i,k}$
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$$\begin{array}{c}
 \begin{array}{ccc}
 \begin{array}{c} \diagup \\ \text{---} T_A \\ \diagdown \end{array} & \cdot & \begin{array}{c} \color{red} X \\ \color{red} X \end{array} & \cdot & \begin{array}{c} \color{red} \diagdown \\ T_B \\ \color{red} \diagup \end{array} & + & \begin{array}{ccc}
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 \end{array}
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$X_{11}$	...	$X_{1,k-i}$	...	$X_{1k}$
$\vdots$	$\ddots$	$\vdots$	$\vdots$	$\vdots$
$X_{k-i,1}$	...	$X_{k-i,k-i}$	...	$X_{k-i,k}$
$\vdots$	$\ddots$	$\vdots$	$\ddots$	$\vdots$
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$O(n^3)$

# Systems of generalized $\star$ -Sylvester equations

## Goal 1:

Obtain **necessary and sufficient conditions** for **uniqueness of solution** of **systems** of equations of the form  $AXB + CX^{\star}D = E$  (with both  $X = Y$  or  $X \neq Y$ ) and  $\star = 1, \top, *$ .

## Goal 2:

Write an **algorithm** to compute the unique solution.

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👉 More on this at the forthcoming [ILAS2016](#) Conference in Leuven



- 
-  F. DE TERÁN, B. IANNAZZO, *Uniqueness of solution of a generalized  $\star$ -Sylvester matrix equation*, LAA 493 (2016)
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# THANKS FOR YOUR ATTENTION !!!!!